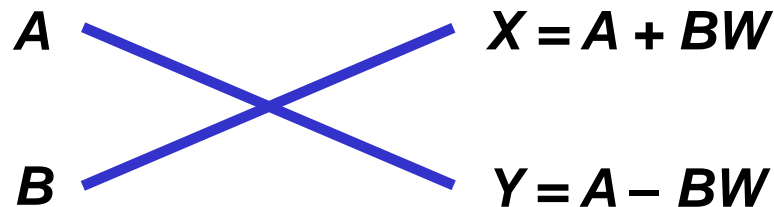


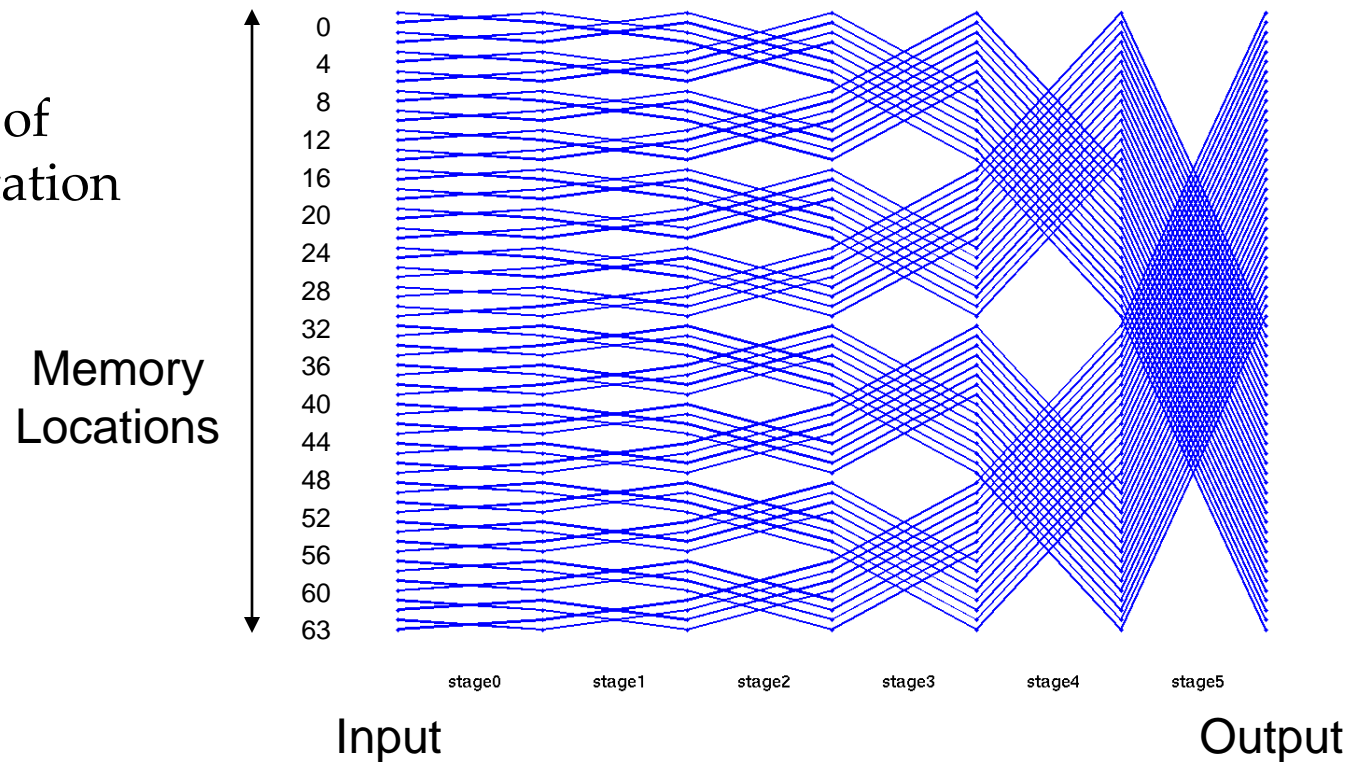
FFT

- There are many ways to decompose an FFT [Rabiner and Gold]
- The simplest ones are radix-2
- Computation made up of radix-2 butterflies

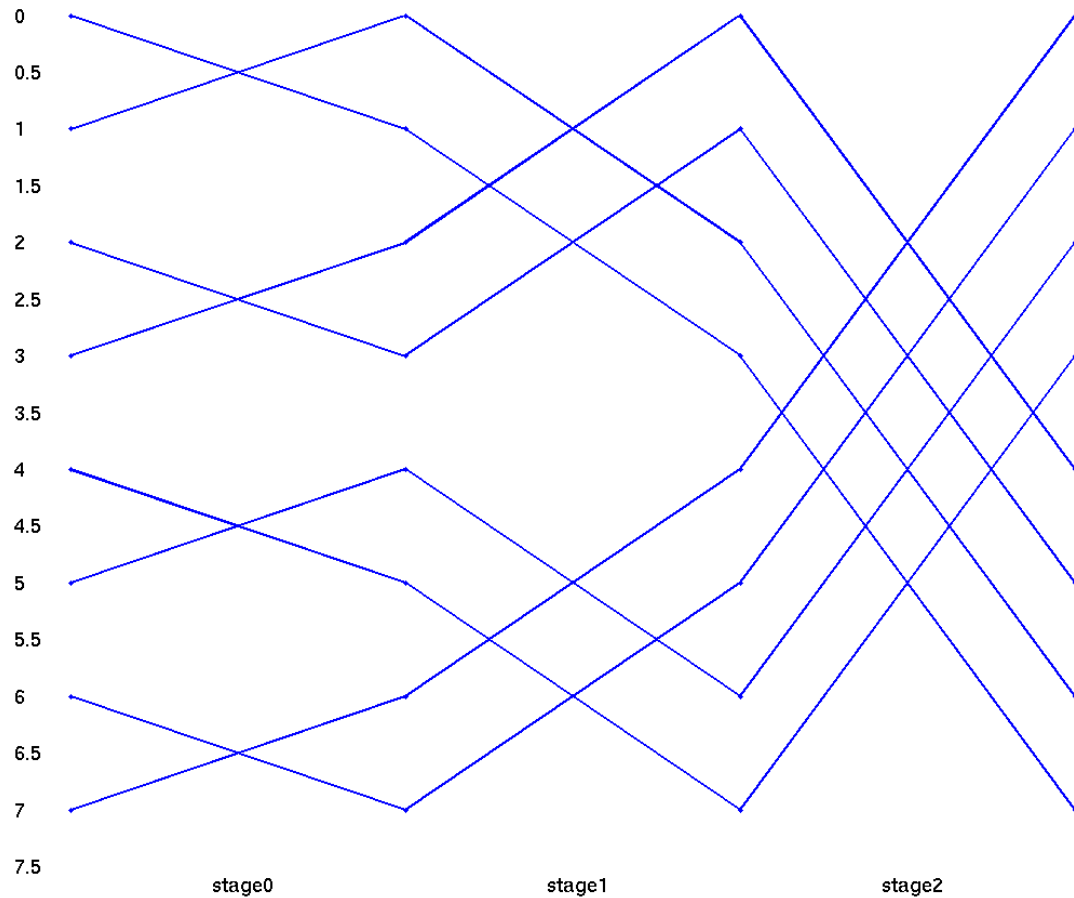


FFT Dataflow Diagram

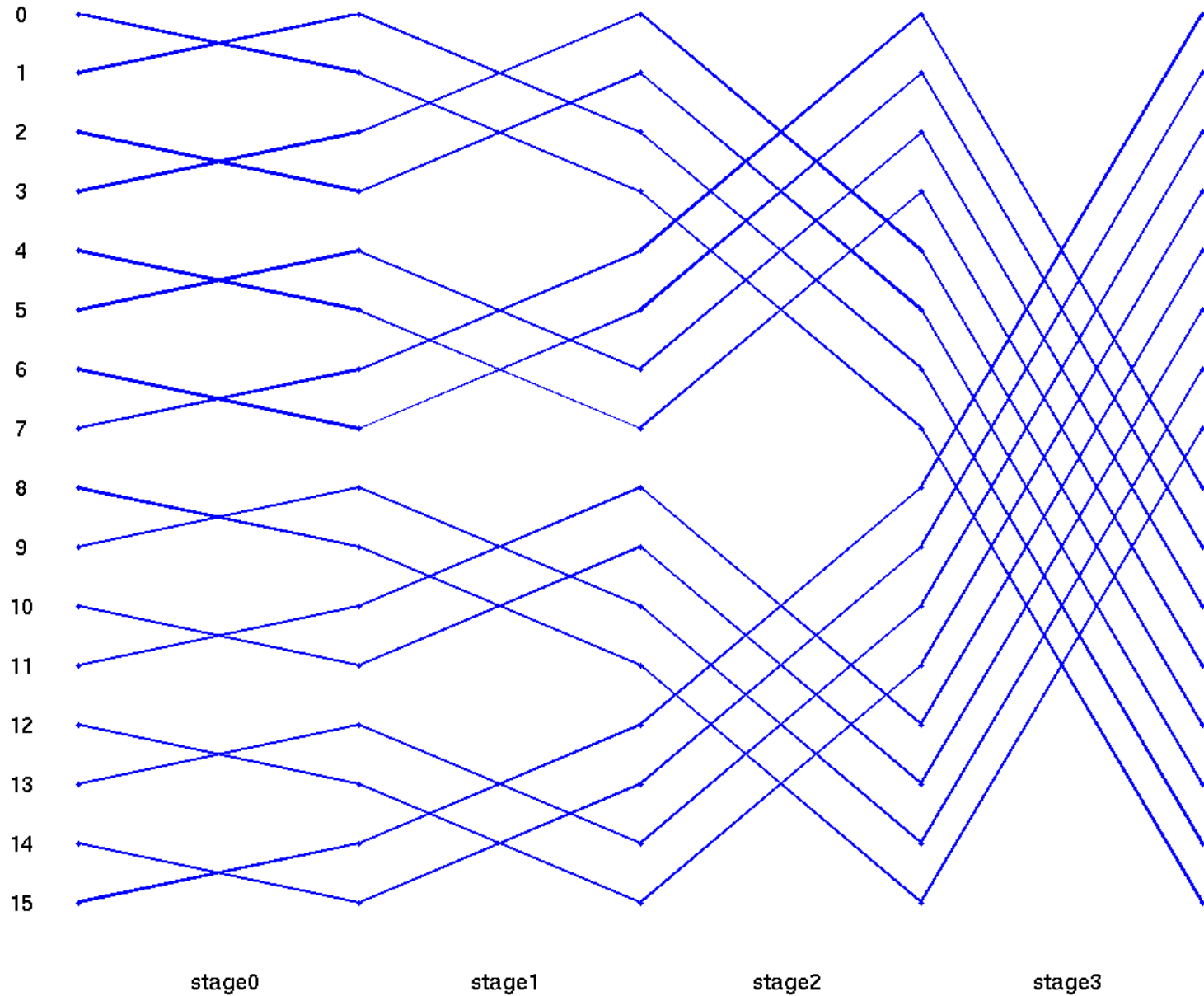
- Dataflow diagram
 - $N = 64$
 - radix-2
 - 6 *stages* of computation



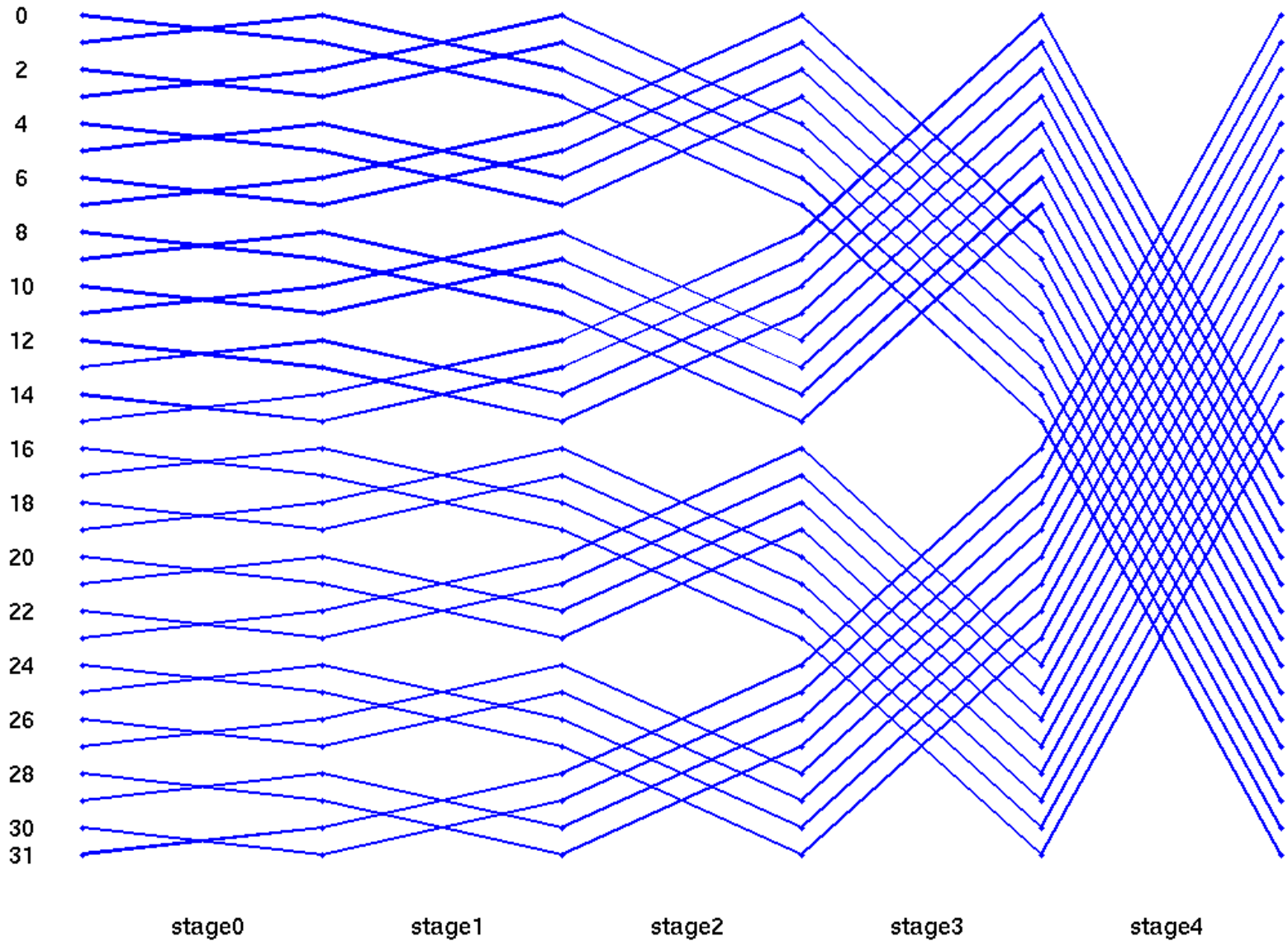
Radix 2, 8-point FFT



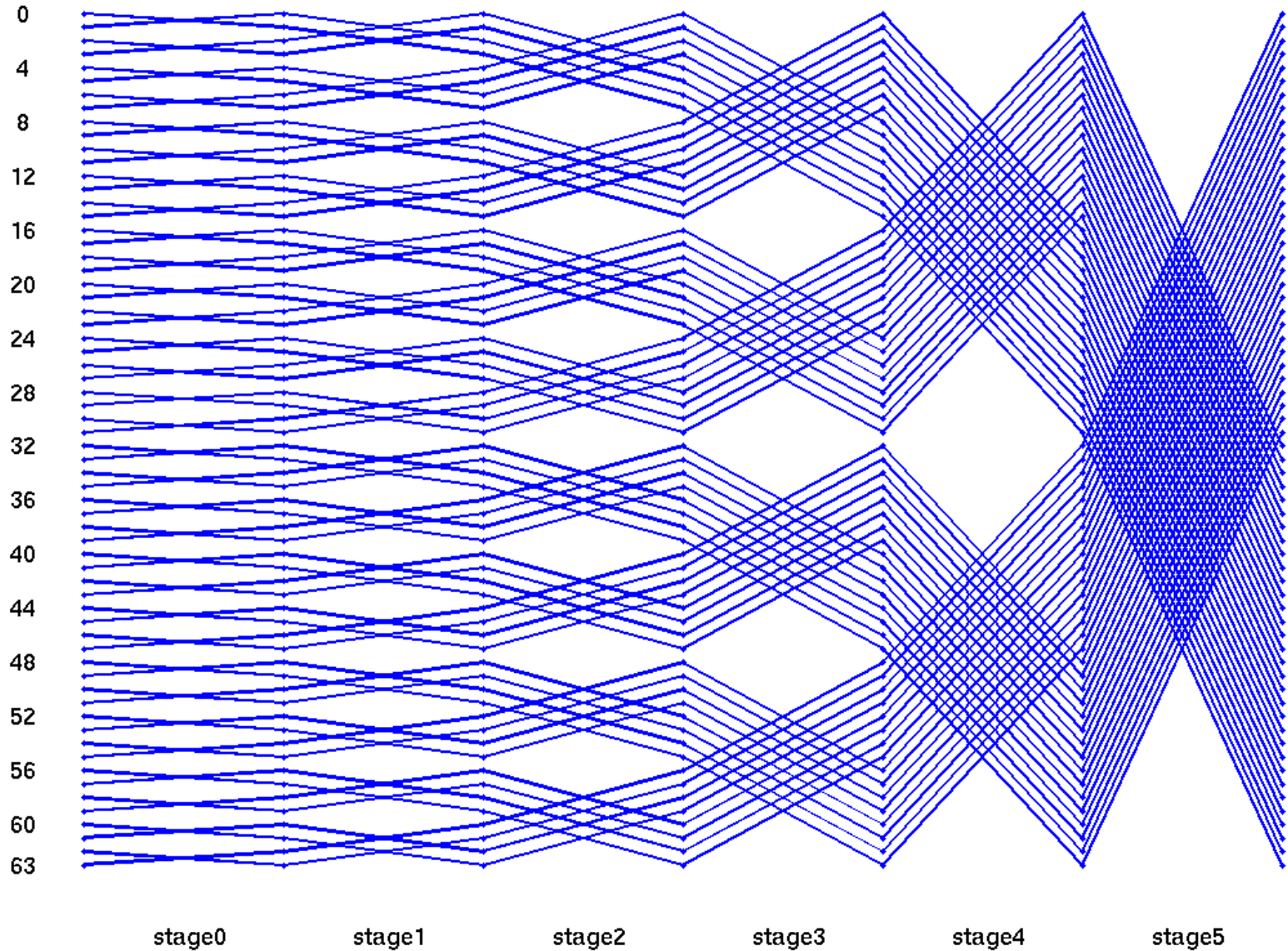
Radix 2, 16-point FFT



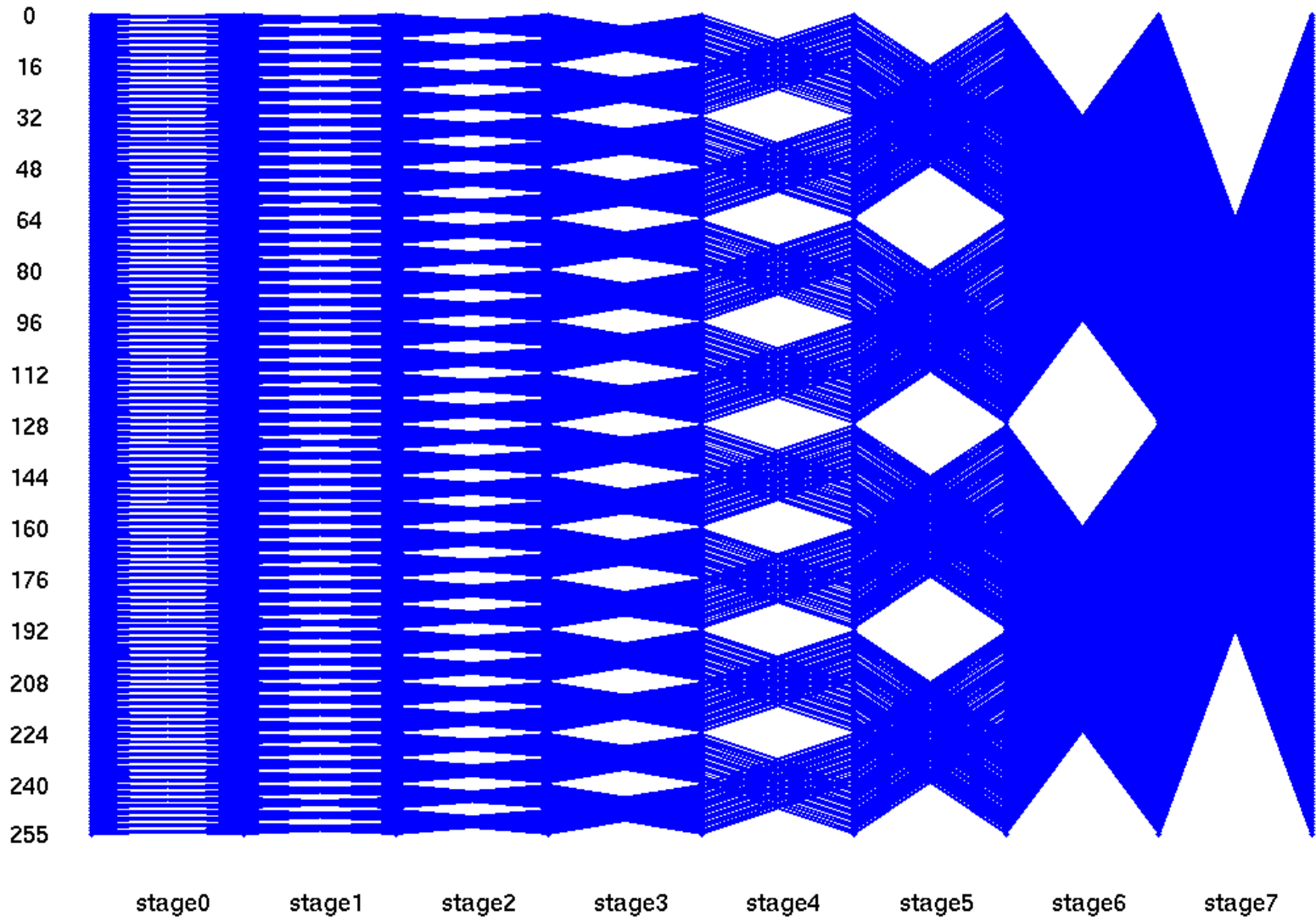
Radix 2, 32-point FFT



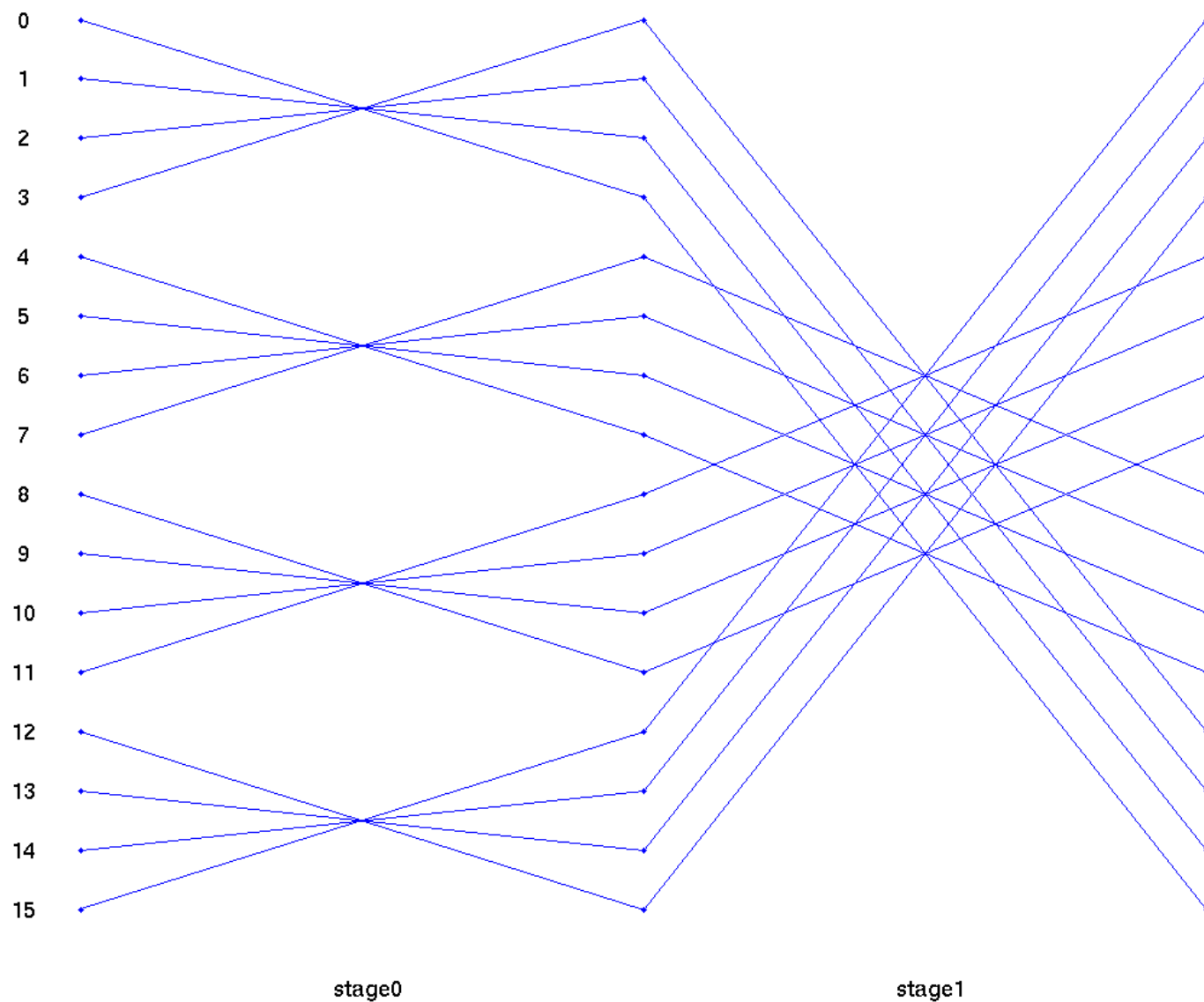
Radix 2, 64-point FFT



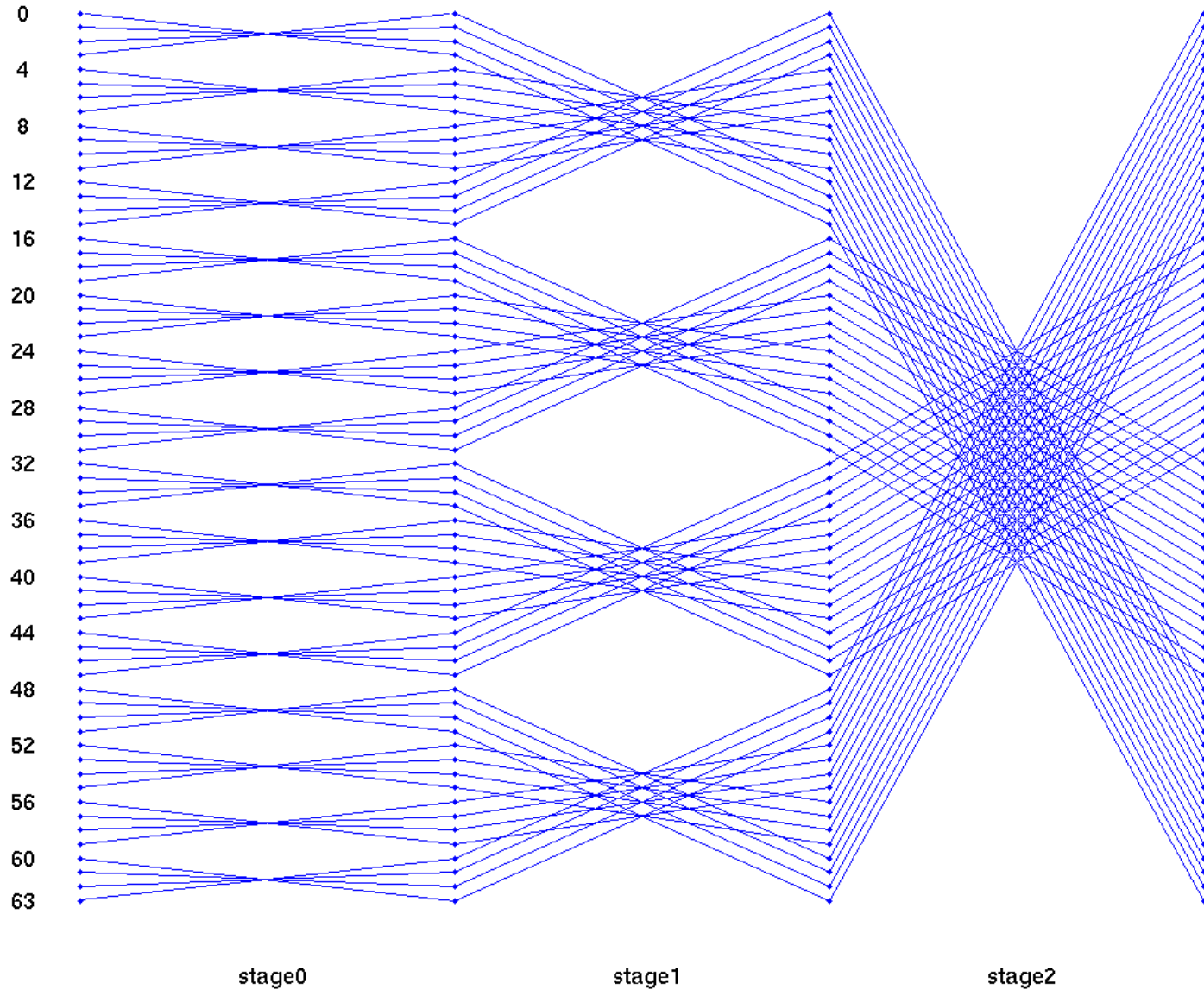
Radix 2, 256-point FFT



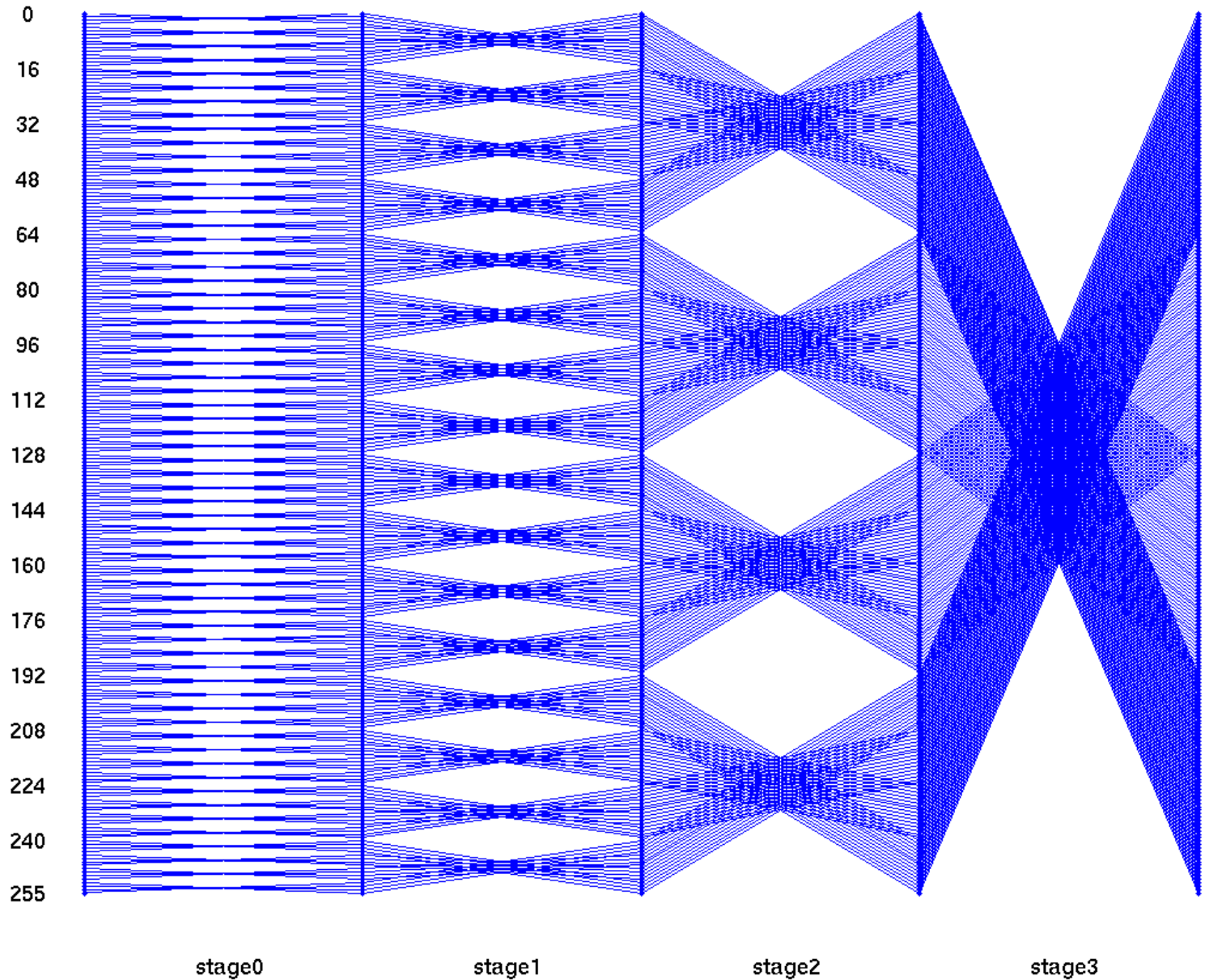
Radix 4, 16-point FFT



Radix 4, 64-point FFT

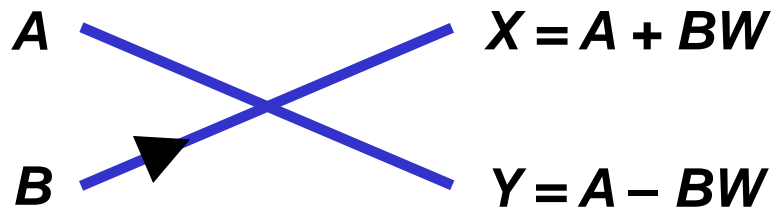


Radix 4, 256-point FFT

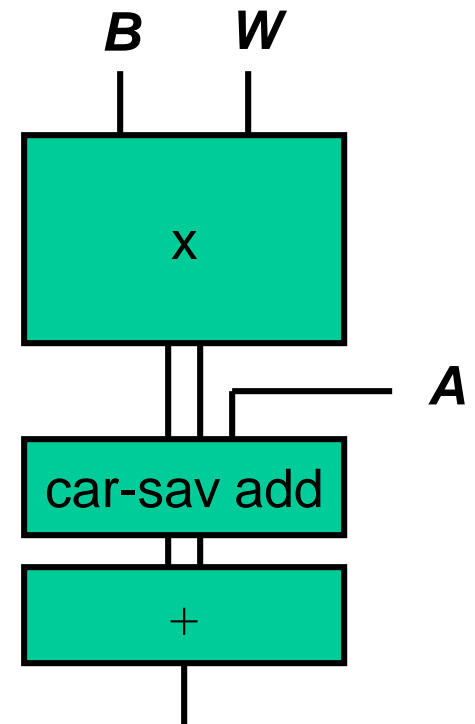


Radix 2, Decimation-In-Time (DIT)

- Input order “decimated” — needs bit reversal
- Output in order
- Butterfly:

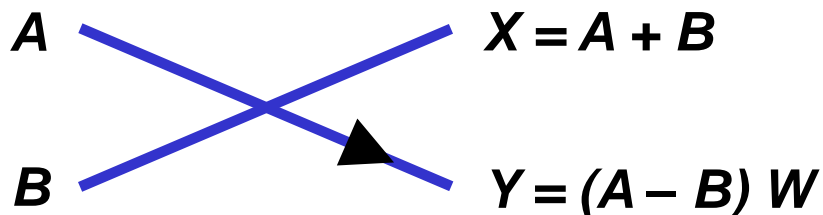


Critical path:

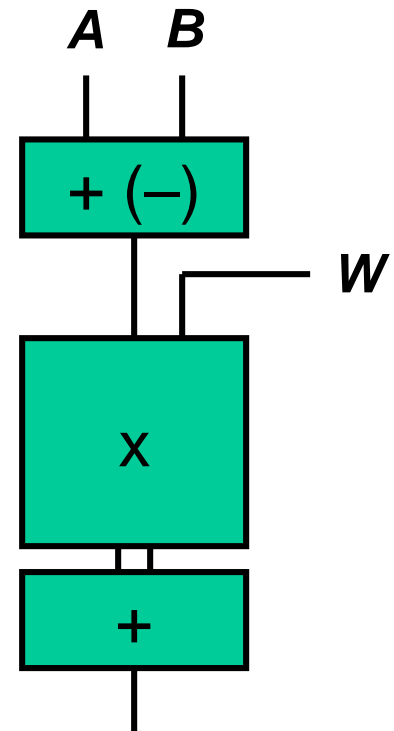


Radix 2, Decimation In Frequency (DIF)

- Input in order
- Output “decimated” —needs bit reversal
- Butterfly:
 - Two CPAs
 - Wider multiplier

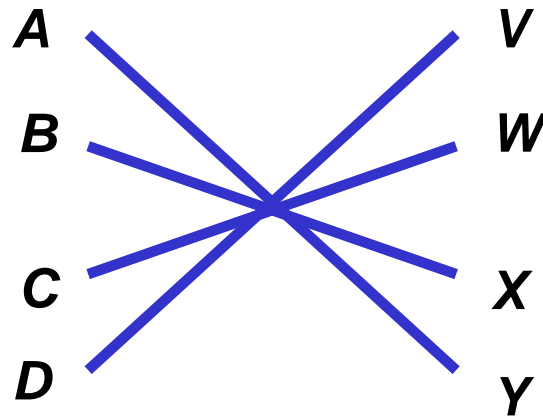


Critical path:



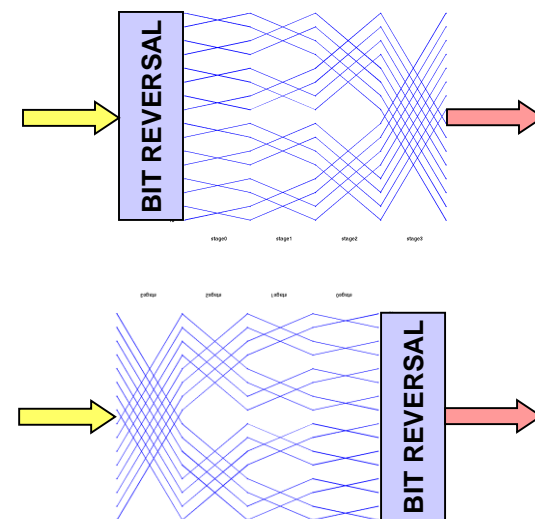
Radix 4, DIT Butterfly

- Decimation in Time (DIT) or Decimation in Frequency (DIF)



Bit-Reversed Addressing

- Normally:
 - DIT: bit-reverse inputs before processing
 - DIF: bit-reverse outputs after processing



- Reverse addressing bits for read/write of data
 - 000 (0) → 000 (0) # Word 0 does not move location
 - 001 (1) → 100 (4) # Original word 1 goes to location 4
 - 010 (2) → 010 (2) # Word 2 does not move location
 - 011 (3) → 110 (6) # Original word 3 goes to location 6
 - 100 (4) → 001 (1) # Original word 4 goes to location 1
 - 101 (5) → 101 (5) # Word 5 does not move location
 - 110 (6) → 011 (3) # Original word 6 goes to location 3
 - 111 (7) → 111 (7) # Word 7 does not move location

Addressing In Matlab

(Especially helpful for FFTs)

- Matlab
 - Matlab can not index arrays with index zero!
- In matlab, do address calculations normally
 - $AddrA = 0, 2, 4, \dots$
 $AddrB = 1, 3, 5, \dots$
- then use pointers with an offset of one whenever indexing arrays
 - $AddrA = \dots;$
 $AddrB = \dots;$
 $A = \text{data}(AddrA+1);$
 $B = \text{data}(AddrB+1);$
 \dots
 $\text{data}(AddrA+1) = X;$
 $\text{data}(AddrB+1) = Y;$

Higher Radices

- Radix 2 and radix 4 are certainly the most popular
- Radix 4 is on the order of 20% more efficient than radix 2 for large transforms
- Radix 8 is sometimes used, but longer radix butterflies are not common because additional efficiencies are small and added complexity is non-trivial (especially for hardware implementations)

I. Common-Factor FFTs

- Key characteristics
 - Most common class of FFTs
 - Also called Cooley-Tukey FFTs
 - Factors of N used in decomposition have common factor(s)
- A) Radix- r
 - $N = r^k$, where k is a positive integer
 - Butterflies used in each stage are the same
 - Radix- r butterflies are used
 - N/r butterflies per stage
 - $k = \log_r N$ stages

I. Common-Factor FFTs

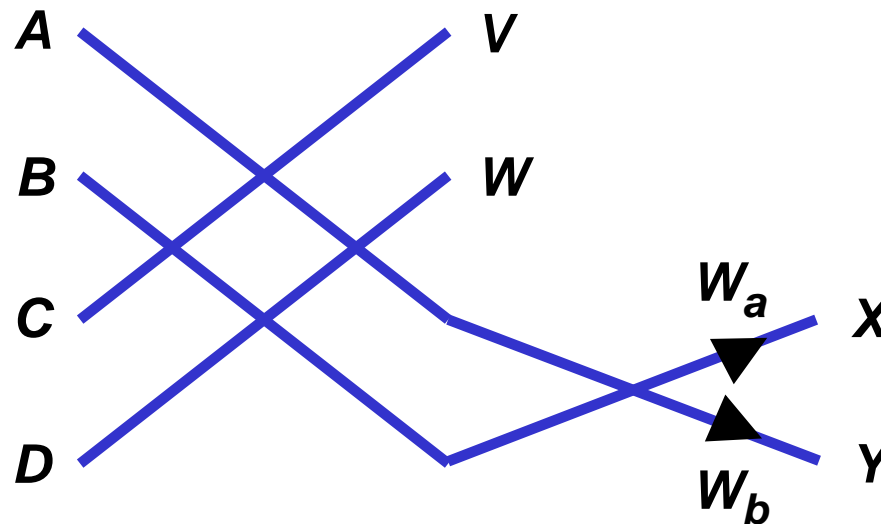
- B) Mixed-radix
 - Radices of component butterflies are not all equal
 - More complex than radix- r
 - Is necessary if $N \neq r^k$
 - Example
 - $N = 32$
 - Could calculate with two radix-4 stages and one radix-2 stage

II. Prime-Factor FFTs

- The length of transforms must be the product of relatively prime numbers
- This can be limiting, though it is often possible to find lengths near popular power-of-2 lengths (e.g., $7 \times 11 \times 13 = 1003$)
- Their great advantage is that they have no W_N twiddle factor multiplications
- Irregular sorting of input and output data
- Irregular addressing for butterflies

III. Other FFTs

- Split-radix FFT
 - When $N = p^k$, where p is a small prime number and k is a positive integer, this method can be more efficient than standard radix- p FFTs
 - “Split-radix Algorithms for Length- p^m DFT’s,” Vetterli and Duhamel, *Trans. on Acoustics, Speech, and Signal Processing*, Jan. 1989



III. Other FFTs

- Winograd Fourier Transform Algorithm (WFTA)
 - Type of prime factor algorithm based on DFT building blocks using a highly efficient convolution algorithm
 - Requires many additions but only order N multiplications
 - Has one of the most complex and irregular structures
- FFTW (www.fftw.org)
 - C subroutine libraries highly tuned for specific architectures
- Goertzel DFT
 - Not a “normal” FFT in that its computational complexity is still order N^2
 - It allows a subset of the DFT’s N output terms to be efficiently calculated

Signal Growth

- Note in DFT equation signal can grow by N times
- This is also seen in the FFT in its growth by r times in a radix- r butterfly, and $\log_r N$ stages in the entire transform: $r^{\log_r N} = N$
- Thus, the FFT processor requires careful scaling
 - Floating point number representation
 - Easiest conceptually, but expensive hardware. Typically not used in efficient DSP systems.
 - Fixed-point with scaling by $1/r$ every stage
 - First stage is a special case. Scaling must be done on the inputs before processing to avoid overflow with large magnitude complex inputs with certain phases.
 - Block floating point

Efficient Computation of the IFFT

- `out = IFFT(in)`
- 0) Design a separate processor for IFFTs
- Re-use a forward FFT engine if available
 - 1) Swapping real and imaginary parts:
`a = fft(imag(in) + i*real(in));`
`out = (imag(a) + i*real(a));`
 - 2) Using conjugates:
`a = fft(conj(in));`
`out = conj(a);`
 - 3) A simple indexing change:
`a = fft(in);`
`out = [a(0) a(N-1:-1:1)]; % with normal indices`
`out = [a(1) a(N :-1:2)]; % with weird matlab indices`