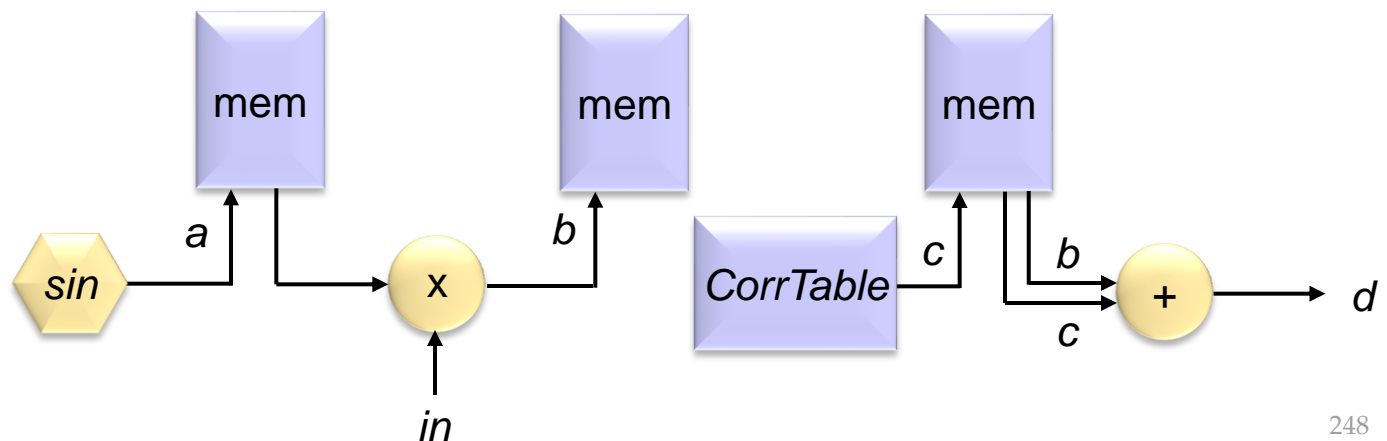


DRIVE THROUGH PROCESSING

“Drive thru” Data Processing

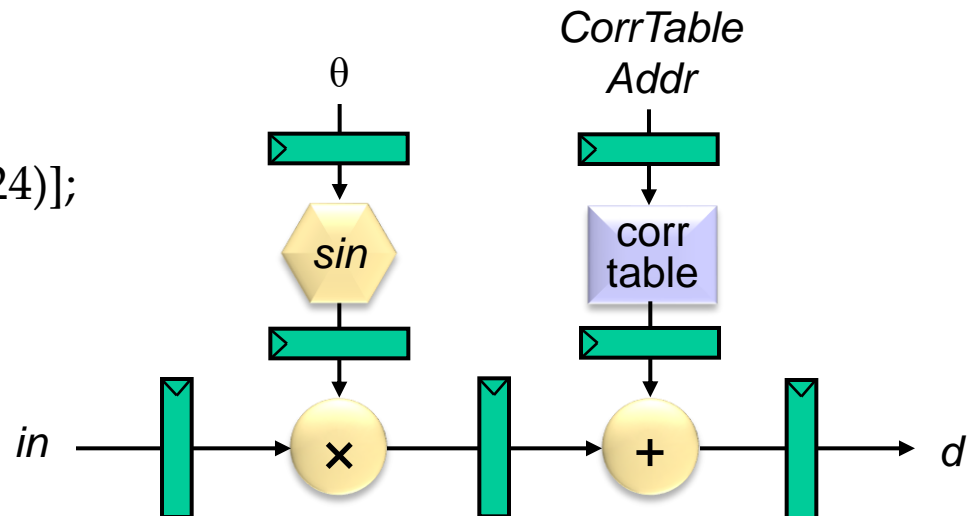
- Example implementation using a “standard high-level programming language”
 - Allocate memory space for temporary variables
 - Perform one complete task at a time and move data between buffers
 - Wastes lots of energy (power) on communication and memories
 - Ex: $a = \sin(1:1024);$
 $b = in(1:1024) \cdot a(1:1024);$
 $c = \text{CorrectionTableMem}[\text{addr}(1:1024)];$
 $d = b + c;$



“Drive thru” Data Processing

- Example implementation for an efficient real-time processing system
 - Process data as it flows by
 - Don't store any more data than is absolutely necessary
 - Don't request/generate data until exactly the cycle it is needed
 - Ex:

```
a = sin( $\theta$ );  
b = in * a;  
c = CorrTableMem[addr(1:1024)];  
d = b + c;
```



“Drive thru” Data Processing

- I used to call this “Drive by” data processing—not a very nice name, but it does give a better sense of data flowing along and getting processed as it passes by
- Don’t picture an In-N-Out Burger drive thru with cars lined up waiting
- Picture an automatic car wash where cars get pulled along at a *constant rate* and various steps are applied as cars pass by various stations:
 - 1) Soap applied
 - 2) Brushes
 - 3) Rinse
 - 4) Dry
- Multiple cars are cleaned at the same time which looks just like a pipelined datapath



“Drive thru” Data Processing

- The previous diagram illustrates the way data flows from input (*in* primarily) to the output (*d*) but it is not a valid pipelined block diagram