EEC 216 Lecture #4: Low Power Circuits

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Outline

• Announcements
• Review: Power Estimation, Interconnect Power
• Lecture 3: Low Power Architecture
• Static CMOS Logic
• Ratioed CMOS Logic
• Pass Gate Logic
Announcements

• Guest lecture this Friday, Jan. 18
  – Nate Guilar on Microwatt Power Electronics
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Review: High Level Power Estimation

- **Basic Idea:** Estimate components of dynamic power before completing design
  1. Use results from past experience, instruction profiling
  2. Benchmark designs from literature (e.g., power factor)
  3. Complexity metrics to estimate capacitance (e.g., area, entropy)
  4. Profiling, statistical modeling to estimate activity factor (e.g., dual bit type method)

- **Advantages:** feedback on power early in design process, can use relative information without requiring absolute accuracy

- **Disadvantages:** usually ignore timing-related activity (glitching), absolute accuracy often needed (e.g. package selection, system power budget)
Review: Interconnect Power

- **Resistance**: depends on material resistivity, wire cross-section, length to width ratio

- **Capacitance**: two terms – parallel-plate and fringing field capacitances
  - As technology scales, fringing fields more important
  - Empirical formula for accounting for both components
  - Miller effect: data dependent charging of mutual capacitances between adjacent wires

- **Wire length must be estimated to approximate interconnect power early in design process**
  - Several approaches based on empirical studies of wire length for different circuit blocks
  - Rent’s Rule: empirical formula relating gates to I/O’s
Review: Low Power Architecture

• Clock Gating
  – Simple to implement, common industry practice

• Power Down Modes
  – Extend clock gating to gating supply voltages

• Parallelization

• Pipelining

• Bit Serial vs. Bit Parallel Datapaths
  – Low transistor count of serial arithmetic yields less leakage power for increased dynamic power, but net power reduction
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Summary of CMOS Logic Styles

• Nonclocked Logic
  – Does not require clock for proper logic operation (although clocks may be required for state operation)
  – Static CMOS, ratioed logic, DCVSL, Pass-Gate logic

• Clocked Logic
  – Periodic signal required for correct logic operation as well as for state (latches and flip-flops)
  – Dynamic logic, DCSL

• Clocked styles faster in general, but also consume more power (can be observed in Power-Delay Product)
• Pull-Up network consists of PMOS devices connected complementary to NMOS Pull-Down network
Static CMOS Two-Input NAND Gate
NMOS Logic Rules

Series NMOS

Parallel NMOS

$A \cdot B$

$A + B$
PMOS Logic Rules

Series PMOS

\[ A \cdot B = A + B \]

Parallel PMOS

\[ A + B = A \cdot B \]
Static CMOS Logic Design

- Think of transistor as ideal switch controlled by gate
  - NMOS ON when gate high, OFF when gate low
  - PMOS OFF when gate high, ON when gate low
- Design NMOS or PMOS network first to implement desired logic function
- Design complementary network by recursively using duality
- Complementary CMOS is naturally inverting
  - Requires extra inverter stage to realize noninverting gate
- N-input logic gate requires 2N transistors
Complex Gate Example (on board)

\[ F = D + A \cdot (B + C) \]
Static CMOS for Low Power

- Dynamic power and short circuit current applies
  - Mismatched delays can lead to glitching, increased dynamic power
  - Dynamic logic eliminates glitches, short circuit
- Only static power due to leakage
- Fully complementary design has high noise margin
  - $V_{OH} = V_{DD}$, $V_{OL} = GND$
  - Design style more scalable to lower supply voltages
  - Implies lower threshold voltages can be used also
- PMOS devices may degrade performance
  - High input capacitance, slow series P-stacks
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• Pull-Up network replaced by simple (often resistive) load
NMOS Two-Input NAND Gate

- Depletion NMOS always on, sourcing static current
Pseudo-NMOS Two-Input NAND Gate

- PMOS always on, sourcing static current
Ratioed Logic for Low Power

- Dynamic power and static current applies
  - Mismatched delays can lead to glitching, increased dynamic power
  - Conducts current as long as output is low
- Reduced noise margin because of resistance ratios
  - $V_{OH} = V_{DD}$, $V_{OL} = R_{PDN} / (R_L + R_{PDN})$
  - Could increase leakage in load gates whose NMOS gates are at $V_{OL}$ instead of ground
- Reduced transistor count decreases input capacitance
- Low-to-High transition speed determined by load (could be faster or slower than series PMOS)
- Most useful for high fan-in gates
Data Dependent Static Power

- Static power dissipated whenever output is low
- Dynamic power dissipated only on output low-to-high transition
  - For static CMOS 2-input NAND:
  
  \[
  \alpha_{0\rightarrow1} = \frac{3}{16} = 0.1875
  \]
  
  - For pseudo-NMOS 2-input NAND (assume uniform, independent inputs):
    
    \[
    \alpha_0 = p_A p_B = 0.25
    \]
  
  - 33% higher activity factor for pseudo-NMOS
A Better Ratioed Logic Style

- Can eliminate static current and provide rail-to-rail output swings
  - Must change load device into a load circuit
  - Need two concepts: differential logic plus positive feedback
- Each gate generates true and complement outputs
  - Two mutually exclusive NMOS pulldown networks implemented in parallel
  - Only one conducts at a time
- Single PMOS pullup replaced by cross-coupled PMOS devices
  - Positive feedback pulls output to VDD, eliminates static current
Differential Cascode Voltage Switch Logic

- PDN1 ON implies PDN2 OFF pulls $Out$ low, turning on PMOS which pulls complement high
DCVSL Summary for Low Power

• Differential logic style
  – Generating both polarities of output can improve speed (eliminates inverters)
  – Extra noise immunity to common-mode noise
  – Convenient for self-timed (asynchronous) logic design

• Still a ratioed logic style, even though outputs transition rail-to-rail
  – PMOS must be sized carefully to ensure functionality
  – Pulldown networks must overcome PMOS on other side

• Short circuit current flows while outputs are switching (pulldown fighting opposite side PMOS)

• Twice the number of NMOS inputs compared to single-ended ratioed logic styles, higher input capacitance
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Pass-Transistor Logic Design

• Logic families studied so far connect primary inputs to transistor gates only

• New circuit concept: connect primary inputs to sources and drains as well as gates
  – Intuition is that it will reduce number of devices required to implement any given logic function

• Consider 2-input AND gate example:

\[ F = A \cdot B \]
Pass-Transistor Design Issues

• B inverse path needed for static output
  – Otherwise output would be high impedance:

\[ F = A \cdot \overline{B} \]

• Needs only two devices as opposed to six for static CMOS 2-input AND

• Requires generating complement of B with additional inverter
**Cascading Pass-Transistor Gates**

- **Bottom approach is correct way to cascade pass gate logic, maximizes output high swing.**

\[ V_{OH} = V_{DD} - V_{Tn} \]

\[ V_{OH} = V_{DD} - 2V_{Tn} \]
• Since complementary signals needed anyway, can create a fully differential version of pass gate logic
CPL Basic Gates: AND / NAND

\[ F = A \cdot B \]

\[ \overline{F} = \overline{A} \cdot \overline{B} \]
CPL Basic Gates: OR / NOR

\[ F = A + B \]

\[ \overline{F} = \overline{A + B} \]
CPL Basic Gates: XOR / XNOR

\[ F = A \oplus B \]

\[ \overline{F} = \overline{A \oplus B} \]
Advantages of CPL

• Fully differential signals
  – Requires more devices, but simplifies complex gates like XOR, full adder
  – Both polarities eliminate extra inverters

• Static logic style
  – Output nodes always have a low impedance path to $V_{DD}$ and GND
  – Improves resilience to noise events

• Very modular design style
  – All gates share same fundamental topology
  – Only inputs are permuted
Disadvantages of CPL

- Fully differential signals require extra routing overhead
- Static power dissipation and reduced noise margins due to threshold drop in $V_{OH}$
  - Level restoration through PMOS feedback
  - Multiple-threshold transistors
  - Full transmission gate logic
• PMOS feedback device pulls inverter input to $V_{DD}$
• Must size carefully to guarantee correct operation
  – Pass transistor network must pull $X$ below inverter threshold for output to switch
Multiple-Threshold CPL

- Zero or low threshold NMOS results in almost full rail intermediate nodes
• PMOS devices in parallel with NMOS transistors pass full $V_{DD}$

• Requires more devices, but can be sized smaller than static CMOS
Static CMOS Full Adder

- From Chandrakasan92, “Low-Power CMOS Digital Design”
Complementary Pass Gate Logic Full Adder

From Chandrakasan92, “Low-Power CMOS Digital Design”
PDP vs. Delay for Various Circuit Forms

Fig. 4. Data showing improvement in power–delay product at the cost of speed for various circuit approaches.

- From Chandrakasan92, “Low-Power CMOS Digital Design”
Complementary Pass-Gate Logic for Low Power

• Number of devices can be dramatically lower than static CMOS
  – No static power if circuits designed to maximize swings
• Extra routing overhead implies extra capacitance
• Performance worse than other styles, especially when gates cascaded
  – Acceptable when aggressive voltage scaling reaches limits, then only way to reduce power is to reduce switched capacitance
  – Power-Delay Product (switching energy) lower than for other styles
Closing Thoughts

• Static CMOS is almost always the right choice
  – Simple to design, very robust wrt noise, power supply variation
  – Use other styles only sparingly and with care (bag of tricks for special cases of low area, low leakage, etc.)

• Next topic: sizing, dynamic logic, clocking